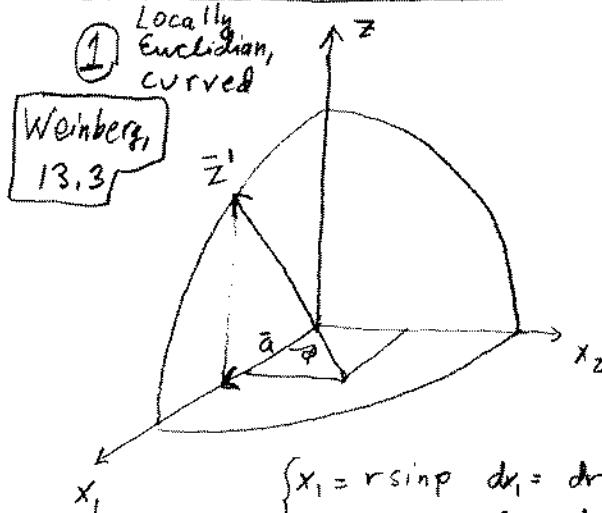


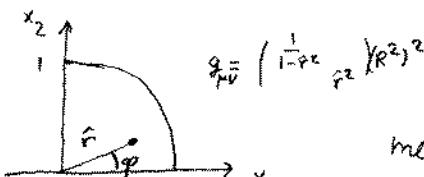
## Metrics by imbedding



$$\begin{cases} x_1 = r \sin \varphi & dx_1 = dr \cdot \sin \varphi + r \cos \varphi d\varphi \\ x_2 = r \cos \varphi & dx_2 = dr \cdot \cos \varphi - r \sin \varphi d\varphi \end{cases}$$

$$x_1 dx_1 + x_2 dx_2 = r dr$$

$$dx_1^2 + dx_2^2 = dr^2 + r^2 d\varphi^2$$



$$V = \int d^2 \sqrt{g} = \int dr d\varphi \frac{r R^2}{\sqrt{1-r^2}} = \pi R \int_0^1 \frac{dy}{\sqrt{1-y^2}} = 2\pi R^2 = \frac{1}{2} (\text{Area of sphere})$$

metric in

$$x_1^2 + x_2^2$$

$$\begin{aligned} z^2 + \bar{x}^2 &= R^2 \\ \Rightarrow z dz + \bar{x} d\bar{x} &= 0 \end{aligned}$$

Metric

$$\begin{aligned} ds^2 &= dz^2 + dx_1^2 + dx_2^2 \\ &= \frac{(x_1 dx_1 + x_2 dx_2)^2}{R^2 - \bar{x}^2} + dx_1^2 + dx_2^2 \\ &= \frac{r^2 dr^2}{R^2 - r^2} + dr^2 + r^2 d\varphi^2 \\ &= \frac{dr^2}{R^2 - r^2} + r^2 d\varphi^2 \end{aligned}$$

$$ds^2 = R^2 \left[ \frac{dr^2}{1 - \hat{r}^2} + \hat{r}^2 d\varphi^2 \right]$$

It seems the origin is a special point. However by rotating  $z \rightarrow \bar{z}'$  you can bring the origin to any point  $\bar{a}$  on the sphere  $(\bar{0}, 1) \rightarrow (\bar{a}, \sqrt{1-\bar{a}^2})$

$$\begin{cases} \bar{x}' = \bar{x} + \bar{a} / (z - b \bar{x} \cdot \bar{a}) & \bar{x}'^2 + \bar{z}'^2 = \bar{x}^2 + z^2 \text{ if } b = \frac{1 - \sqrt{1 - \bar{a}^2}}{\bar{a}^2} \\ z' = \sqrt{1 - \bar{a}^2} z - \bar{a} \cdot \bar{x} \end{cases}$$

We will generalize this to

$$\begin{cases} z^2 - y_1^2 - \dots - y_m^2 + y_{m+1}^2 = R^2 \Rightarrow AdS_{m+1} & (\text{in the space of } y_1 \dots y_{m+1}) \\ + z^2 + y_1^2 + \dots + y_m^2 - y_{m+1}^2 = R^2 \Rightarrow dS_{m+1} & (- \dots -) \end{cases}$$

but start from known RW (where the above is the spatial part!)

$$m=1 \quad \begin{cases} z^2 - y_1^2 + y_2^2 = R^2 \\ z^2 + y_1^2 - y_2^2 = R^2 \end{cases} \quad \begin{matrix} AdS_2 \\ dS_2 \end{matrix} \quad \text{just the same: } R = R_P = 0 \text{ for } m=1 \quad p. 34$$

hep-th/0212396  
deSitter, anti deSitter from RW

Start from RW:

$$d\tau^2 = dt^2 - R^2(t) \left[ \frac{dr^2}{1-kr^2} + r^2(d\theta^2 + \sin^2\theta d\phi^2) \right]$$

with  $\begin{cases} \ddot{R} = -\frac{4\pi G}{3}(\varepsilon + 3p)R \text{ "acceleration"} \\ \dot{R}^2 + k = \frac{8\pi G}{3}\varepsilon R^2 \text{ "energy"} \end{cases}$

and only cosmological constant  $= \varepsilon_{vac} = -P_{vac}$

Conventions:  $T^{\mu\nu} = \varepsilon_{vac} g^{\mu\nu}$

$$\Lambda = 8\pi G \varepsilon_{vac} \quad \dim \Lambda = \frac{1}{5^2}$$

$$\Rightarrow \boxed{\dot{R}^2 + k = \frac{\Lambda}{3} R^2}$$

$$\begin{array}{lll} k = -1 & \text{open} & \varepsilon < \varepsilon_{cr} \\ k = +1 & \text{closed} & \varepsilon > \varepsilon_{cr} \end{array}$$

$$\begin{cases} k=0 & \dot{R}^2/R^2 = \frac{\Lambda}{3} \quad \text{must be } \Lambda > 0 & R/t = e^{\pm\sqrt{\frac{\Lambda}{3}}t} \\ \Lambda > 0 & R = \sqrt{\frac{3}{\Lambda}} \operatorname{sh} \sqrt{\frac{\Lambda}{3}}t & \dot{R} = \operatorname{ch} \sqrt{\frac{\Lambda}{3}}t \quad \dot{R}^2 = \operatorname{sh}^2 \sqrt{\frac{\Lambda}{3}}t + 1 = \frac{\Lambda}{3} R^2 + 1 \quad k=-1 \\ \Lambda > 0 & = \sqrt{\frac{3}{\Lambda}} \operatorname{ch} \sqrt{\frac{\Lambda}{3}}t & \dot{R} = \operatorname{sh} \sqrt{\frac{\Lambda}{3}}t \quad \dot{R}^2 = \operatorname{ch}^2 \sqrt{\frac{\Lambda}{3}}t - 1 = \frac{\Lambda}{3} R^2 - 1 \quad k=+1 \end{cases}$$

Claim: All these sol's are deSitter space but in different coordinates!

$$\Lambda < 0 \quad \dot{R}^2 + k = -\frac{|\Lambda|}{3} R^2 \Rightarrow k = -1 \quad R/t = \sqrt{-\frac{\Lambda}{3}} \sin \sqrt{-\frac{\Lambda}{3}} t$$

$$G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = -\Lambda g_{\mu\nu} (+8\pi G T_{\mu\nu})$$

same as  $G_{\mu\nu} = 0$   
 with  $T_{\mu\nu} = \frac{\Lambda}{8\pi G} g_{\mu\nu}$

$$\Rightarrow R - \frac{1}{2}g^{\mu\nu}g_{\mu\nu}R = R(1 - \frac{1}{2}d) = -\Lambda d \Rightarrow R = \Lambda \frac{-d}{1 - \frac{1}{2}d} = \Lambda \frac{2d}{d-2}$$

$$R_{\mu\nu} = (\frac{1}{2}R - \Lambda)g_{\mu\nu} = (\frac{d}{d-2} - 1)\Lambda g_{\mu\nu} = \frac{2}{d-2}\Lambda g_{\mu\nu} \quad \Lambda > 0 \text{ for de Sitter}$$

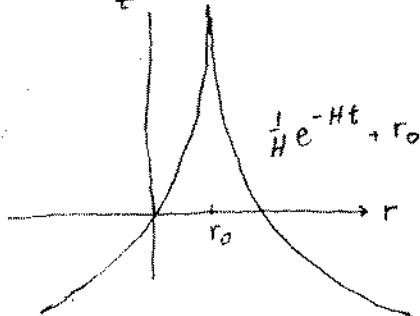
$$R_{\mu\nu\alpha\beta} = \Lambda \frac{g}{(d-1)(d-2)} (g_{\mu\alpha}g_{\nu\beta} - g_{\mu\beta}g_{\nu\alpha})$$

These are valid for all "maximally symmetric spaces", characterised by a "curvature"  $\Lambda$  & signature of metric

### Other forms of de Sitter:

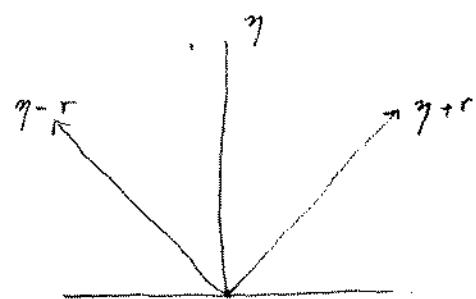
$$1. \quad ds^2 = dt^2 - e^{2Ht} (dr^2 + r^2 d\Omega^2) \quad H^2 = \frac{\Lambda}{3}$$

Light:  $\pm \frac{dt}{dr} e^{-Ht} = dr \quad \pm \frac{1}{H} e^{-Ht} = r - r_0$



$$2. \quad \eta = -\frac{1}{H} e^{-Ht} \quad dt = e^{Ht} d\eta \quad d\eta = e^{-Ht} dt$$

$$ds^2 = \frac{1}{(H\eta)^2} [d\eta^2 - dr^2 - r^2 d\Omega^2]$$



$$3. \quad \text{Static coords} \quad \begin{cases} r = e^{-H\tau} \frac{s}{\sqrt{1-H^2 s^2}} & (dr = r \left[ -Hd\tau + \frac{1}{1-H^2 s^2} \frac{ds}{s} \right]) \\ t = \tau + \frac{1}{2H} \ln(1-H^2 s^2) & (dt = dr - \frac{Hs}{1-H^2 s^2} ds) \\ e^{2Ht} = e^{2H\tau} (1-H^2 s^2) \end{cases}$$

$$ds^2 = (1-H^2 s^2) dr^2 - \frac{1}{1-H^2 s^2} ds^2 - s^2 d\Omega^2 \quad \text{Seems static!}$$

Light  $dr = \frac{1}{1-H^2 s^2} ds$

$$Hs = \tanh H\tau$$



$$Hds = \frac{1}{ch^2 H\tau} Hd\tau$$

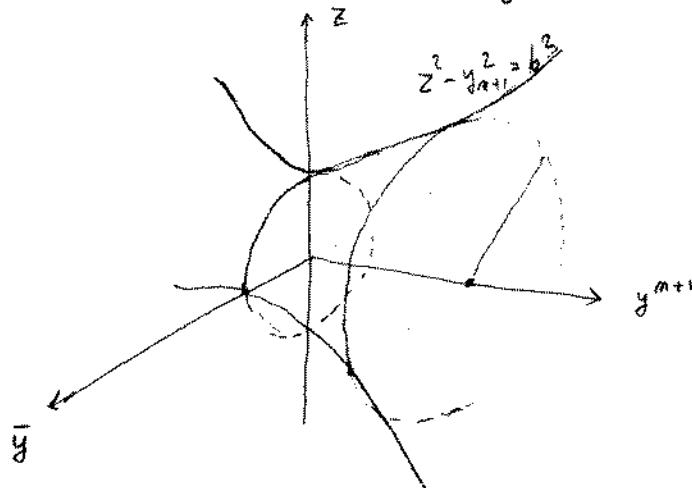
$$= (1 - th^2 H\tau) Hd\tau$$

$$= (1 - H^2 s^2) Hdr$$

Classical geometry of de Sitter  
Kim-Oh-Park hep-th/0212326

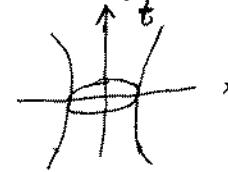
$dS_{m+1}$  with these conventions:

Constraint  $\frac{z^2 + z_1^2 + z_2^2 + z_3^2}{z^2 + \underbrace{y_1^2 + \dots + y_m^2}_{= \bar{y}^2}} - z_0^2 - y_{m+1}^2 = b^2 \quad \leftarrow \text{notation in Birrel-Davis}\right.$  (5.49) for  $dS_4$



Schematically:

$dS:$



$AdS:$



$$(1) \quad \begin{cases} z = b \cosh \frac{t}{b} \\ ds^2 = dz^2 + d\bar{y}^2 - b^2 y^{m+1} \end{cases}$$

$$\begin{cases} y^i = b \sinh \frac{t}{b} & i=1, \dots, m \\ b=1 \end{cases} = (\cosh r dx^M + x^M \sinh r dt)^2 - \cosh^2 r dt^2$$

$$y^{m+1} = b \sinh \frac{t}{b}$$

$$\sum_0^m x_\mu x_\mu = 1$$

$$\Rightarrow x_\mu dx_\mu = 0$$

$$d\omega_m^2 = d\theta_0^2 + \sin^2 \theta_0 d\theta_1^2 + \dots$$

$$\dots + \sin^2 \theta_{m-2} d\theta_{m-1}^2$$

$$ds^2 = -dt^2 + b^2 \cosh^2 \frac{t}{b} d\omega_m^2 = -dt^2 + b^2 \cosh^2 \frac{t}{b} [d\theta_0^2 + \sin^2 \theta_0 (d\theta_1^2 + \sin^2 \theta_2 d\theta_2^2)]$$

$$x^0 = \cosh \theta_0$$

$$(d\theta_1^2 + \sin^2 \theta_2 d\theta_2^2)$$

$$x^1 = \sinh \theta_0 \cos \theta_1$$

$$0 \leq \theta_0 \leq \pi \quad 0 \leq \theta_1 \leq \pi$$

$$x^2 = \sinh \theta_0 \sin \theta_1 \cos \theta_2$$

$$0 \leq \theta_2 \leq 2\pi$$

$$x^{m-1} = \sinh \theta_0 \dots$$

$$\cos \theta_{m-1}$$

$$x^m = \sinh \theta_0 \dots$$

$$\sin \theta_{m-1}$$

$$(2) \quad \begin{cases} z = \sqrt{b^2 - r^2} \cosh \frac{t}{b} \\ y_{m+1} = \sqrt{b^2 - r^2} \sinh \frac{t}{b} \\ z^2 - y_{m+1}^2 = b^2 - r^2 \end{cases} \Rightarrow z^2 + \bar{y}^2 - y_{m+1}^2 = b^2 \quad z + y_{m+1} = \sqrt{b^2 - r^2} e^{\pm t/b} > 0$$

$$\begin{cases} y_1 = \\ y_2 = \\ y_3 = \end{cases} \left. \begin{array}{l} \text{spherical} \\ r \theta \varphi \end{array} \right.$$

$$\bar{y}^2 = r^2$$

$$\left\{ dz = \frac{-r}{\sqrt{b^2 - r^2}} \cosh \frac{t}{b} dr + \sqrt{b^2 - r^2} \frac{1}{b} \sinh \frac{t}{b} dt \right.$$

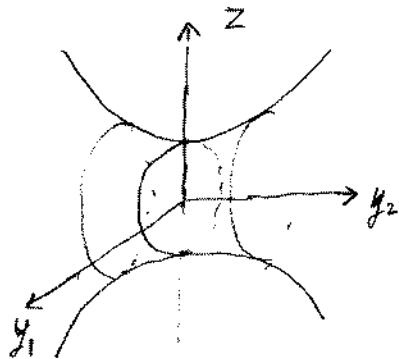
$$\left. dy_{m+1} = \frac{-r}{\sqrt{b^2 - r^2}} \sinh \frac{t}{b} dr + \sqrt{b^2 - r^2} \frac{1}{b} \cosh \frac{t}{b} dt \right.$$

$$ds^2 = -\left(1 - \frac{r^2}{b^2}\right) dt^2 + \frac{r^2}{b^2 - r^2} dr^2 + dr^2 + r^2 (d\theta^2 + \sin^2 \theta d\varphi^2)$$

$$\boxed{ds^2 = -\left(1 - \frac{r^2}{b^2}\right) dt^2 + \frac{1}{1 - \frac{r^2}{b^2}} dr^2 + r^2 d\omega_m^2} = \text{"static" form}$$

AdS by Embedding: see also p.33

as before, but now



dSitter

$$x_1 x_2 \Rightarrow \begin{array}{ccc} - & - & + \\ x^1 x^2 x^3 & & x^{m+1} \end{array}$$

$$\boxed{z^2 + y_1^2 + \dots + y_m^2 - y_{m+1}^2 = R^2}$$

(Weinberg 13.3.39 has

$$g = (+ \underset{++}{\dots} + -) \quad + z^2 + \bar{x}^2 - t^2 = \frac{1}{R^2} = k^2$$

$$\left\{ \begin{array}{l} dt^2 = dt^2 - d\bar{x}^2 - dz^2 \\ zdz + \bar{x} \cdot d\bar{x} - t dt = 0 \end{array} \right.$$

$$d\tau^2 = -dt^2 + d\bar{x}^2 + \frac{(tdt - \bar{x} \cdot d\bar{x})^2}{R^2 + t^2 - \bar{x}^2} \quad (13.3.39) \quad R^2 = \frac{1}{k}$$

$$\left\{ \begin{array}{l} t = R \left[ \frac{1}{2} F'^2 \cosh \bar{x}^2 + (1 + \frac{1}{2} F'^2) \sinh \bar{x}^2 \right] \\ \bar{x} = \bar{x}' e^{\frac{F}{R}} \end{array} \right. \quad F = \frac{r}{R} \text{ etc}$$

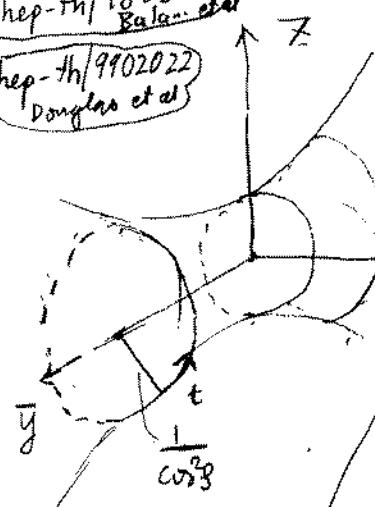
$$\Rightarrow \boxed{d\tau^2 = dt'^2 - e^{2\bar{x}'} d\bar{x}'^2} = \text{flat RW metric}$$

AdS by embedding

Now start from  $(+ - \dots - +) = \eta_{ab}$

See  
hep-th/9805171  
Balasubramanian et al

hep-th/9902022  
Douglas et al



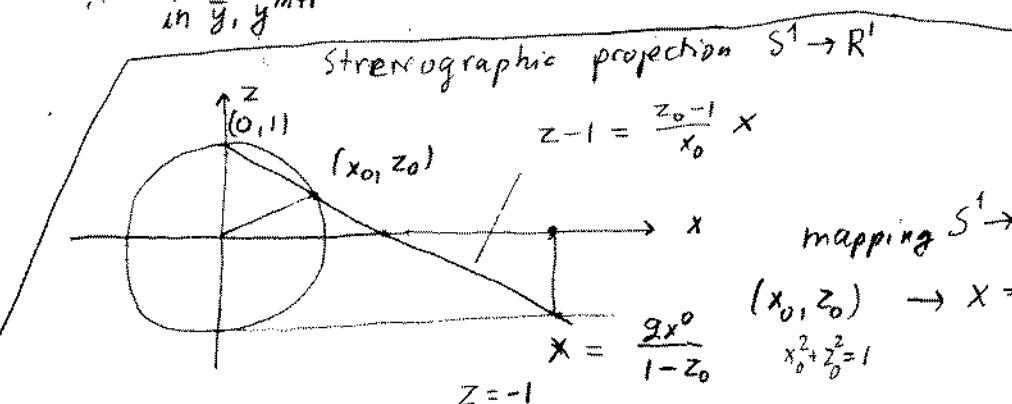
- induces AdS<sub>m+1</sub>  
in  $\bar{y}_i, y^{m+1}$

z      y-bar      t  
or:  $y^0 \quad y^i \quad y^{m+1}$

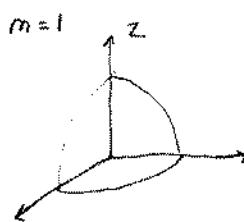
$$\boxed{z^2 - \bar{y}^2 + (y^{m+1})^2 = b^2}$$

One could compute  
 $ds^2 = g_{\mu\nu} dy^\mu dy^\nu$  as  
above but it is more

convenient to directly introduce new  
coordinates satisfying this constraint



$$\textcircled{1} \text{ Implement } z^2 - \bar{y}^2 + (y^{m+1})^2 = b^2 \quad (=1) \quad z^2 + (y^{m+1})^2 = b^2 \geq b^2$$

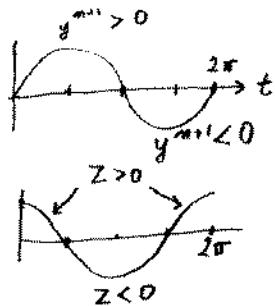


by

$$z_i = \frac{\cos t}{\cos \varphi}, \quad y^i = z_i \tan \varphi, \quad y^{m+1} = \frac{\sin t}{\cos \varphi}, \quad \sum_{i=1}^m z_i^2 = 1$$

$\tan \varphi > 0, \cos \varphi > 0$

$$\frac{\cos^2 t + \sin^2 t}{\cos^2 \varphi} - \sum_{i=1}^m z_i^2 \tan^2 \varphi = \frac{1}{\cos^2 \varphi} - \tan^2 \varphi = 1$$

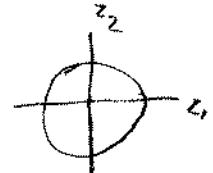


$$0 \leq t < 2\pi \quad 0 \leq \varphi \leq \frac{\pi}{2} \quad z_i \in S^{m-1}$$

angle around circle  $\Rightarrow$  radius of the circle

$$y^i \text{ on } z, y^{m+1} \text{ plane} = \frac{1}{\cos^2 \varphi}$$

$\frac{\pi}{2}$



$$ds^2 = (dz)^2 - dy^2 + (dy^{m+1})^2$$

$$= \left( -\frac{\sin^2 t}{\cos^2 \varphi} dt^2 + \cos^2 t \frac{\sin^2 \varphi}{\cos^2 \varphi} d\varphi^2 \right) - \sum_i \left( \tan \varphi dz_i + z_i \frac{1}{\cos^2 \varphi} d\varphi \right)^2$$

$$+ \left( \frac{\cos^2 t}{\cos^2 \varphi} dt + \sin t \frac{\sin \varphi}{\cos^2 \varphi} d\varphi \right)^2$$

$$\Rightarrow -ds^2/R^2 = -\frac{1}{\cos^2 \varphi} dt^2 + \frac{1}{\cos^2 \varphi} d\varphi^2 + \tan^2 \varphi dL_{m-1}^2$$

$dL_{m-1}$  surf. element  
of  $S^{m-1}$

 $m=2:$ 

$$\text{AdS}_3 \quad -\frac{ds^2}{R^2} = -\frac{1}{\cos^2 \varphi} dt^2 + \frac{1}{\cos^2 \varphi} d\varphi^2 + \tan^2 \varphi d\varphi^2$$

line

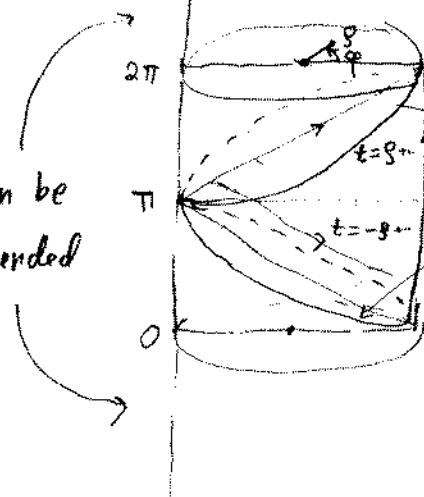
disc

surface (cylinder) is a boundary at spatial infinity

light:  $dt = \pm d\varphi \Rightarrow t = \pm \varphi + C$   
what happens at  $\varphi = 0$ ?

CFT on cylinder  
= quantum gravity  
in bulk

$t$  can be  
extended



Boundary  
of  $\text{AdS}_{m+1}$  is  $t, S^{m-1}$  = cylinder

$\text{AdS}_5 \Rightarrow t, S^3$

$\rightarrow R^{m+1}$  by adding points at  $\infty$

(2) Here is a 2nd way of enforcing

$$z^2 - y_1^2 - \dots - y_m^2 + y_{m+1}^2 = R^2 :$$

$$\boxed{Z = g \frac{1+x^2}{1-x^2} \quad y^i = g \frac{x^i}{1-x^2} \quad y^{m+1} = g \frac{x^{m+1}}{1-x^2}}$$

$$g^2 \frac{1}{(1-x^2)^2} \left[ (1+x^2)^2 - 4x^2 + 4(x^{m+1})^2 \right] = g^2$$

$$\text{if } x^2 = \bar{x}^2 - (x^{m+1})^2 = \gamma_{\mu\nu} x^\mu x^\nu$$

$$\begin{cases} dz = dg \frac{1+x^2}{1-x^2} + g \frac{2}{(1-x^2)^2} 2x_\mu dx^\mu & d \frac{x^\mu}{1-x^2} \\ dy^\mu = dg \frac{2x^\mu}{1-x^2} + \underbrace{2g \left[ \frac{1}{1-x^2} dx^\mu + x^\mu \frac{2x_\nu dx^\nu}{(1-x^2)^2} \right]}_{+ 2g \frac{1}{(1-x^2)^2} [\delta^\mu_\nu (1-x^2) + 2x^\mu x_\nu]} \\ & dx^\nu \end{cases}$$

$$\Rightarrow dz^2 - \gamma_{\mu\nu} dy^\mu dy^\nu = dg^2 - \frac{4g^2}{(1-x^2)^2} dx^2 \quad \text{Take } g^2 = b^2$$

$$\Rightarrow \boxed{\text{AdS}_{m+1} \text{ is } ds^2 = b^2 \frac{4}{(1-x^2)^2} \underbrace{\gamma_{\mu\nu} dx^\mu dx^\nu}_m (+ + \dots + -)}$$

This metric:

$$g_{\mu\nu} = \frac{4b^2}{(1-x^2)^2} \gamma_{\mu\nu} \quad x^2 = \gamma_{\mu\nu} x^\mu x^\nu$$

should be the extremum of

$$\int d^{m+1}x \sqrt{g} \left[ R + \frac{m(m-1)}{b^2} \right], \text{ i.e., be the solution of}$$

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} \left( R + \frac{m(m-1)}{b^2} \right) = 0$$

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R - \frac{m(m-1)}{2b^2} g_{\mu\nu} = 0 \quad \Lambda = -\frac{m(m-1)}{2b^2}$$

This looks like a good exercise in  $g_{\mu\nu}$ ,  $\Gamma_{\mu\nu}^{\lambda}$ ,  $R^M_{\nu\sigma}$ :

$$g^{\mu\nu} = e^{-\Phi(x)} \eta^{\mu\nu}$$

$$g_{\mu\nu} = \frac{4b^2}{(1-x^2)^2} \eta_{\mu\nu} = e^{\log 4b^2 - 2\log(1-x^2)} \quad \eta_{\mu\nu} = e^{\Phi(x)} \eta_{\mu\nu}$$

$$\Gamma_{\nu g}^M = \frac{1}{2} g^{M\lambda} \left[ \partial_\nu g_{g\lambda} + \partial_g g_{\nu\lambda} - \partial_\lambda g_{\nu g} \right]$$

$$2\phi \cdot e^\phi \eta_{g\lambda}$$

$$\partial_g | = \frac{1}{2} [\partial_\nu \phi \delta_g^M + \partial_g \phi \delta_\nu^M - \partial^M \phi \eta_{g\lambda}]$$

$$R^M_{\nu g\sigma} = \partial_g \Gamma_{\nu\sigma}^M - \partial_\sigma \Gamma_{\nu g}^M + \underbrace{\Gamma_{\nu g}^M \Gamma_{\nu\sigma}^\lambda}_{\lambda g} - \underbrace{\Gamma_{\nu\sigma}^M \Gamma_{g\lambda}}_{\lambda g}$$

$$[\nabla_g \nabla_\sigma - \nabla_\sigma \nabla_g] V_\nu = + V_\mu R^M_{\nu g\sigma}$$

$$\partial_g \Gamma_{\nu\sigma}^M - \partial_\sigma \Gamma_{\nu g}^M = \frac{1}{2} [\partial_g \partial_\nu \phi \delta_\sigma^M + \partial_g \cancel{\partial_\sigma \phi} \delta_\nu^M - \eta_{\nu\sigma} \partial_g \partial^M \phi - (g \leftrightarrow \sigma)]$$

$$\Gamma_{\lambda g}^M \Gamma_{\nu\sigma}^\lambda - (g \leftrightarrow \sigma) = \frac{1}{4} (\partial_\lambda \phi \delta_g^M + \partial_g \phi \delta_\lambda^M - \partial^M \phi \eta_{g\lambda}) / (\partial_\nu \phi \delta_\sigma^\lambda + \partial_\sigma \phi \delta_\nu^\lambda - \partial^\lambda \phi \eta_{\nu\sigma}) - (1)$$

$$\begin{aligned} &= \frac{1}{4} [\partial_\sigma \phi \partial_\nu \phi \delta_g^M + \partial_\nu \phi \partial_\sigma \phi \delta_g^M - \partial_\nu \phi \partial^M \phi \delta_g^M \eta_{\nu\sigma} \\ &\quad + \partial_g \phi \partial_\nu \phi \delta_\sigma^M + \cancel{\partial_g \phi \partial_\sigma \phi} \delta_\nu^M - \cancel{\partial_g \phi} \partial^M \phi \eta_{\nu\sigma} \\ &\quad - \cancel{\partial^M \phi} \partial_\nu \phi \eta_{g\sigma} - \cancel{\partial^M \phi} \partial_\sigma \phi \eta_{g\sigma} + \partial^M \phi \cancel{\partial_\sigma \phi} \eta_{\nu\sigma} - (g \leftrightarrow \sigma)] \end{aligned}$$

$$\begin{aligned} &= \frac{1}{4} [2\partial_\nu \phi \partial_\sigma \phi \delta_g^M - \delta_g^M (\partial \phi)^2 \eta_{\nu\sigma} + \partial_g \phi \partial_\nu \phi \delta_\sigma^M - \cancel{\partial_g \phi} \cancel{\partial_\sigma \phi} \eta_{\nu\sigma} - \cancel{\partial^M \phi} \cancel{\partial_\sigma \phi} \eta_{g\sigma} + \cancel{\partial^M \phi} \cancel{\partial_\sigma \phi} \eta_{\nu\sigma} \\ &\quad - 2\partial_\nu \phi \partial_g \phi \delta_\sigma^M + \delta_\sigma^M (\partial \phi)^2 \eta_{\nu g} - \cancel{\partial_g \phi} \partial_\nu \phi \delta_\sigma^M + \cancel{\partial_\sigma \phi} \cancel{\partial_\nu \phi} \eta_{\nu g} + \partial^M \phi \cancel{\partial_\sigma \phi} \eta_{\nu\sigma} - \cancel{\partial^M \phi} \cancel{\partial_\sigma \phi} \eta_{g\sigma}] \end{aligned}$$

$$= \frac{1}{4} [\partial_\nu \phi \partial_\sigma \phi \delta_g^M - \partial_\nu \phi \partial_g \phi \delta_\sigma^M + \partial^M \phi \partial_g \phi \eta_{\nu\sigma} - \partial^M \phi \partial_\sigma \phi \eta_{g\sigma} + \delta_\sigma^M (\partial \phi)^2 \eta_{\nu g}]$$

For general  $\phi(x)$ ,  $g_{\mu\nu} = e^{\Phi(x)} \eta_{\mu\nu}$ , from the above  $- \delta_g^M (\partial \phi)^2 \eta_{\nu\sigma}$

$$R_{\mu\nu} = (1 - \frac{d}{2}) (\partial_\mu \partial_\nu \phi - \frac{1}{2} \partial_\lambda \phi \partial_\lambda \phi) + \frac{1}{2} \eta_{\mu\nu} [(1 - \frac{d}{2}) \partial_\lambda \phi \partial^\lambda \phi - 2 \partial^\lambda \phi]$$

$$= R_{\mu \underline{\nu} \sigma \rho}$$

For the present  $\phi(x) = \text{const} - 2\log(1-x^2)$ :

$$\begin{cases} \partial_r \phi \partial_v \phi = \frac{16x_r x_v}{A^2} \\ \partial_r \partial_v \phi = \frac{4}{A} \eta_{rv} + \frac{8}{A^2} x_r x_v \end{cases} \quad A \equiv 1-x^2$$

$$\begin{aligned} R^M_{\nu g \sigma} &= \frac{1}{2} \left[ \left( \frac{4}{A} \eta_{gv} + \frac{8}{A^2} x_g x_v \right) \delta M_\sigma - \eta_{v\sigma} \left( \frac{4}{A} \delta M_g + \frac{8}{A^2} x_g x_v \right) \right. \\ &\quad \left. - \left( \frac{4}{A} \eta_{ov} + \frac{8}{A^2} x_o x_v \right) \delta M_g + \eta_{vg} \left( \frac{4}{A} \delta M_\sigma + \frac{8}{A^2} x_o x_v \right) \right] + R^P - P^P \\ &= \frac{1}{2} \left[ \delta M_\sigma \left( \frac{8}{A} \eta_{vg} + \boxed{\frac{8}{A^2} x_v x_g} \right) - \delta M_g \left( \frac{8}{A} \eta_{v\sigma} + \frac{8}{A^2} \cancel{x_o} x_v \right) \right. \\ &\quad \left. - \frac{8}{A^2} \eta_{v\sigma} \cancel{x_g x_v} + \frac{8}{A^2} \eta_{vg} \cancel{x_o x_v} \right] \\ &\quad + \frac{1}{4} \left\{ \frac{16}{A^2} \cancel{x_v x_g} \delta M_g \left[ -\frac{16}{A^2} x_v x_g \delta M_\sigma \right] + \frac{16}{A^2} x^M x_g \eta_{v\sigma} - \frac{16}{A^2} x^M x_o \eta_{vg} \right. \\ &\quad \left. + \delta M_\sigma \eta_{vg} \frac{16x^2}{A^2} - \delta M_g \eta_{v\sigma} \frac{16x^2}{A^2} \right\} \\ &= \frac{4}{A} (\delta M_\sigma \eta_{vg} - \delta M_g \eta_{v\sigma}) + \frac{4x^2}{A^2} (\delta M_\sigma \eta_{vg} - \delta M_g \eta_{v\sigma}) \\ &= \frac{4}{A} \left( 1 + \frac{x^2}{A} \right) (\delta M_\sigma \eta_{vg} - \delta M_g \eta_{v\sigma}) = + \frac{4}{(1-x^2)^2} (\delta M_\sigma \eta_{vg} - \delta M_g \eta_{v\sigma}) \\ R^M_{\nu g \sigma} &= \frac{4}{(1-x^2)^2} (\delta M_\sigma \eta_{vg} - \delta M_g \eta_{v\sigma}) = \frac{1}{b^2} (\delta M_\sigma g_{vg} - \delta M_g g_{v\sigma}) \end{aligned}$$

$$\boxed{\frac{1}{b^2} g_{\mu\nu} = \frac{4}{(1-x^2)^2} \eta_{\mu\nu}}$$

$$D \equiv m+1$$

$$\Rightarrow R_{\mu g} = R_{\mu v g \sigma} = \frac{1}{b^2} \left( \delta_{\mu\sigma} \delta_g^\sigma - \delta_{\mu\sigma} \underset{=D}{\delta_g^\sigma} \right) = \frac{1}{b^2} g_{\mu g} \left( 1 - (m+1) \right) = -\frac{m}{b^2} g_{\mu g}$$

$$R = -\frac{1}{b^2} m(m+1) = \frac{2(m+1)}{m-1} \Lambda = \frac{2d}{d-g} \Lambda < 0$$

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = -\frac{m}{b^2} g_{\mu\nu} + \frac{1}{2} g_{\mu\nu} \frac{1}{b^2} m(m+1) = \frac{1}{b^2} g_{\mu\nu} \left( -m + \frac{1}{2}(m^2+m) \right) = \frac{m(m+1)}{2b^2} g_{\mu\nu}$$

$$\boxed{R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R - \frac{m(m+1)}{2b^2} g_{\mu\nu} = 0} \Rightarrow \boxed{\Lambda = "8\pi G \epsilon_{vac}" = -\frac{m(m+1)}{2b^2} < 0}$$

③ 3rd way of implementing ("Poincaré coordinates")

$$z^2 - y_1^2 - y_2^2 - \dots - y_{m-1}^2 - y_m^2 + y_{m+1}^2 = b^2$$

$$\left. \begin{array}{l} b \frac{t}{r} \\ b \frac{x_1}{r} \\ b \frac{x_2}{r} \\ b \frac{x_{m-1}}{r} \\ \frac{1}{2r} (-b^2 + \bar{x}^2 + r^2 - t^2) \end{array} \right\} y_m + y_{m+1} = -\frac{b^2}{r} \leq 0$$

$$\boxed{-\infty \leq t \leq \infty \quad 0 \leq r \leq \infty \quad -\infty < x_i < \infty}$$

$$-\frac{1}{2r} (b^2 + \bar{x}^2 + r^2 - t^2)$$

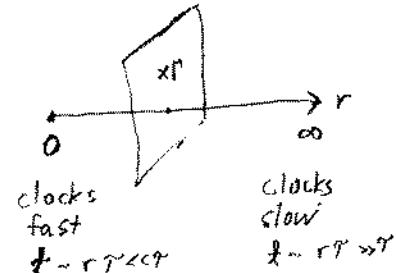
$$\frac{b^2}{r^2} (t^2 - \bar{x}^2) - \frac{1}{4r^2} [(-b^2 + \bar{x}^2 + r^2 - t^2)^2 - (b^2 + \bar{x}^2 + r^2 - t^2)^2] \\ - 4b^2 (\bar{x}^2 + r^2 - t^2)$$

$$= \frac{b^2}{r^2} [t^2 - \bar{x}^2 + (\bar{x}^2 + r^2 - t^2)] = b^2 !$$

$\boxed{\text{AdS}_{m+1} \text{ is}}$

$$\Rightarrow ds^2 = \frac{b^2}{r^2} (-dt^2 + dx_1^2 + \dots + dx_{m-1}^2 + dr^2)$$

warp factor      inv. under  $x^M = (x^I, r)$        $\rightarrow \lambda x^M$



Again conformally flat!

Exercise:  $ds^2 = e^{\phi(x^m)} \eta_{\mu\nu} dx^\mu dx^\nu \quad x^0, x^1, \dots, x^{m-1}, x^m$

$$\phi(x) = \log^2 - 2 \log(x^m) \quad g_{\mu\nu} = \frac{b^2}{x^m} \eta_{\mu\nu} \quad \partial_\mu \phi = -\frac{2}{x^m} \delta_\mu^m$$

bottom of p. 35:

$$\partial_\mu \partial_\nu \phi = \frac{2}{(x^m)^2} \delta_\mu^m \delta_\nu^m$$

$$R_{\mu\nu} = \left(1 - \frac{d}{2}\right) \underbrace{\left(\frac{2}{(x^m)^2} \delta_\mu^m \delta_\nu^m - \frac{1}{2} \cdot \frac{4}{(x^m)^2} \delta_\mu^m \delta_\nu^m\right)}_{=0} + \frac{1}{2} \eta_{\mu\nu} \underbrace{\left[ \left(1 - \frac{d}{2}\right) \frac{4}{(x^m)^2} \delta_\mu^m \delta_\nu^m - \frac{2}{(x^m)^2} \delta_\mu^m \delta_\nu^m \right]}_{\eta_{\mu\nu} \cdot \frac{1}{(x^m)^2} (1-d)}$$

Compare (p. 151):

$$R_{\mu\nu} = -\frac{d-1}{(x^m)^2} \eta_{\mu\nu} = -\frac{d-1}{b^2} g_{\mu\nu}$$

as should for  $\text{AdS}_{m+1}$      $d = m+1$

$$\begin{aligned} ds^2 &= \frac{r^2}{R^2} \eta_{\mu\nu} dx^\mu dx^\nu + \frac{R^2}{r^2} dr^2 + R^2 d\Omega_5^2 \\ &= \frac{r^2}{R^2} \left[ \eta_{\mu\nu} dx^\mu dx^\nu + \left( \frac{R^2}{r^2} dr \right)^2 + \frac{R^4}{r^2} d\Omega_5^2 \right] \\ &= \frac{R}{g^2} \left( \eta_{\mu\nu} dx^\mu dx^\nu + dg^2 \right) + R^2 d\Omega_5^2 \quad \frac{dg^2}{g^2} = -\frac{r}{R} \\ &\quad \text{back to the above!} \end{aligned}$$