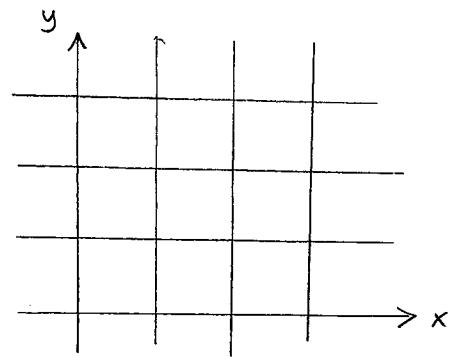


## Y1. Flat-Sky Approximation

- Consider just a small part of the sphere (or of the sky, if we are thinking at the observer approach (2)), where we can ignore the curvature: We use Euclidean geometry and introduce Cartesian coords  $x$  and  $y$ .



- Now  $P_{ab}(x,y) = +\frac{1}{2} \begin{bmatrix} Q & U \\ U & -Q \end{bmatrix} = \begin{bmatrix} P_{xx} & P_{xy} \\ P_{yx} & P_{yy} \end{bmatrix} = \begin{bmatrix} P_{xx} & P_{xy} \\ P_{xy} & -P_{xx} \end{bmatrix}$  (5)

We can introduce a vector field  $w^a$  related to the polarization field  $P_{ab}$ , by taking the divergence:

$$w^a \equiv p_{,b}^{ab} = p_{,b}^{ba}$$
 (6)

(it doesn't matter whether am index is up or down, since we use Cartesian coords).

If we do a Fourier transformation on this 2-d plane, the divergence becomes

$$w^a = ik_b p^{ab}, \quad \text{or} \quad (7)$$

$$\begin{bmatrix} w^x \\ w^y \end{bmatrix} = \begin{bmatrix} ik_x p^{xx} + ik_y p^{xy} \\ ik_x p^{yx} + ik_y p^{yy} \end{bmatrix} = \begin{bmatrix} ik_x p^{xx} + ik_y p^{xy} \\ ik_x p^{xy} - ik_y p^{xx} \end{bmatrix} = i \begin{bmatrix} k_x & k_y \\ -k_y & k_x \end{bmatrix} \begin{bmatrix} p^{xx} \\ p^{xy} \end{bmatrix}$$

We can now invert this matrix relation:

$$\begin{bmatrix} p^{xx} \\ p^{xy} \end{bmatrix} = -i \begin{bmatrix} k_x & k_y \\ -k_y & k_x \end{bmatrix}^{-1} \begin{bmatrix} w^x \\ w^y \end{bmatrix} = \frac{-i}{k_x^2 + k_y^2} \begin{bmatrix} k_x & -k_y \\ k_y & k_x \end{bmatrix} \begin{bmatrix} w^x \\ w^y \end{bmatrix} \quad (8)$$

Thus the polarization tensor field is determined by this vector field (up to a constant, corresponding to the  $\vec{k} = (k_x, k_y) = 0$  Fourier mode). To express (8) as a derivative in  $\vec{x}$ -space, we need to get rid of the  $k^2 \equiv k_x^2 + k_y^2$ . Thus we define a new vector field  $\vec{v}$  in Fourier space as

$$v^a = \frac{2}{k^2} w^a \quad (9)$$

In  $\vec{x}$ -space this corresponds to solving the  $\vec{V}$  field from the differential equation

$$\nabla^2 \vec{V} = -2 \vec{W} \quad (10)$$

Besides  $\vec{W}$ , the solution depends on the boundary conditions. Using Fourier expansion corresponds to assuming periodic boundary conditions. (When we return to the sphere, there are no boundaries. Also, a constant nonzero linear polarization field on a sphere is not possible, since it unavoidably leads to a singularity at some point.)

Eq. (8) becomes

$$\begin{bmatrix} p_{xx} \\ p_{xy} \end{bmatrix} = -\frac{i}{2} \begin{bmatrix} k_x & -k_y \\ k_y & k_x \end{bmatrix} \begin{bmatrix} V^x \\ V^y \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -ik_x + ik_y \\ -ik_y - ik_x \end{bmatrix} \begin{bmatrix} V^x \\ V^y \end{bmatrix}. \quad (11)$$

○ Returning to  $\vec{x}$ -space, we have

$$\begin{aligned} p_{xx} = -p_{yy} &= -\frac{1}{2} \partial_x V^x + \frac{1}{2} \partial_y V^y \\ p_{xy} = p_{yx} &= -\frac{1}{2} \partial_y V^x - \frac{1}{2} \partial_x V^y \end{aligned} \quad (12)$$

- A vector field can be divided into a curl-free and a divergence-free part. For a 3-dim vector field this can be written as

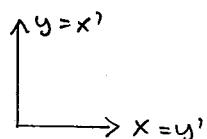
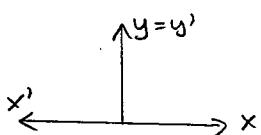
$$\begin{aligned} \vec{V} &= -\nabla A + \nabla \times \vec{B} & \text{or} & \begin{aligned} V_x &= -\partial_x A + \partial_y B_2 - \partial_z B_y \\ V_y &= -\partial_y A + \partial_z B_x - \partial_x B_z \\ V_z &= -\partial_z A + \partial_x B_y - \partial_y B_x \end{aligned} \\ \begin{matrix} \uparrow \\ \text{scalar} \\ \text{potential} \end{matrix} & \begin{matrix} \uparrow \\ \text{vector} \\ \text{potential} \end{matrix} & & \end{aligned} \quad (13)$$

○ We can move towards the 2-dim case by requiring that  $V_z = 0$ , and that the situation is homogeneous in the  $z$ -direction  $\Rightarrow \partial_z = 0$ . From this follows that

$$\begin{aligned} V_x &= -\partial_x A + \partial_y B_z \\ V_y &= -\partial_y A - \partial_x B_z \end{aligned} \quad (14)$$

We can now call  $B \equiv B_z$ . A 2-dim vector field is thus defined by a scalar potential  $A$  and a pseudoscalar potential  $B$ .  $B$  is a pseudoscalar, since it must change sign in a parity transformation, e.g.  $(x' = -x, y' = y)$  or  $(x' = y, y' = x)$ , since this requires  $z' = -z \Rightarrow B_{z'} = -B_z$ , for  $(x, y, z)$  to remain a right-handed

ord. system



Putting (12) and (14) together,

$$\begin{aligned} p^{xx} = -p^{yy} &= +\frac{1}{2} (\partial_x \partial_x A - \partial_x \partial_y B - \partial_y \partial_x A - \partial_y \partial_y B) \\ p^{xy} = p^{yx} &= +\frac{1}{2} (\partial_y \partial_x A - \partial_y \partial_y B + \partial_x \partial_y A + \partial_x \partial_x B) \end{aligned} \quad (15)$$

Using the Levi-Civita tensor  $\epsilon_{ab}$ , whose components in a right-handed Cartesian ind. systems are

$$\epsilon_{ab} = \begin{bmatrix} 0 & 1 & -1 \\ -1 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix} \quad (16)$$

we can write (15) as a single tensor equation (Excuse)

$$P_{ab} = A_{ab} - \frac{1}{2} \delta_{ab} A_{cc} + \frac{1}{2} (\epsilon_{cb} B_{ac} + \epsilon_{ca} B_{bc}) \quad (17)$$

○ which divides the polarization tensor into two parts in a ind-independent way:

- 1) The part given by the scalar field  $A$ , that is called the E-mode, or the gradient mode, and
- 2) the part given by the pseudoscalar field  $B$ , that is called the B-mode, or the curl mode.