

## F. COLLISIONLESS BOLTZMANN EQUATION

### F1. Phase Space and the Distribution Function

- We have seen that treating the matter <sup>(energy)</sup> content of the universe as a fluid described by the energy tensor  $T_{\mu\nu}$  does not lead to a complete set of equations, when the perfect fluid approximation is not valid. Also, this fluid description of the cosmic photon background cannot describe the CMB anisotropy ( $T_{\mu\nu}$  describes multipoles up to  $l=2$  only.)
- Before photon decoupling, baryons and photons behave as a single baryon-photon fluid, for which the perfect fluid approximation is valid.
- During photon decoupling the perfect fluid approximation breaks down, and we require a more detailed treatment of the matter and energy content of the universe.
- For the components (baryons, CDM, neutrinos, photons) which consist of particles this more detailed treatment is provided by the distribution function  $f$  in the 6-dimensional phase space. Each particle species  $i$  has its own distribution function  $f_i$ .
- The phase space is described by six variables:
  - three coordinates  $x^i$
  - and their conjugate momenta  $p_i$
- For our case of particles in a curved spacetime with some coord. system  $x^\mu$ , we can take the coordinates to be the three space coordinates  $x^i$ . The corresponding conjugate momenta are then the covariant space components  $p_i$  of the particle 4-momentum  $\underline{p}$  in the coordinate basis.

- We define the distribution function  $f$  of a particle species as the 6-dimensional number density of these particles in phase space. Thus the number  $dN$  of particles at space coordinates  $x^i$ , within  $dx^1 dx^2 dx^3$ , and with 4-momentum space components  $p_i$ , within  $dp_1 dp_2 dp_3$ , at time  $\eta$ , is given by

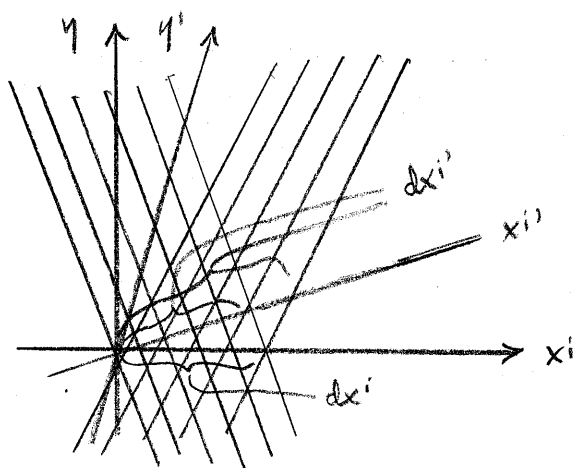
$$dN = f(\eta, x^i, p_i) \underbrace{dx^1 dx^2 dx^3 dp_1 dp_2 dp_3}_{\text{phase space volume element}} \quad (1)$$

Thus  $f$  is a function of time also, but the time coordinate (here  $\eta$ ) appears in a different role than the space coordinates; since  $f$  is defined as a density wrt the space coordinates. So  $f(\eta, x^i, p_i)$  is a function in the 6-dim phase space  $\{x^i, p_i\}$

which evolves in time  $\eta$ . The time component  $p_0$  of the particle 4-momentum does not appear as a variable, since for a given particle species (w given mass  $m$ ),  $p_0$  is determined by the  $p_i$  (and the metric), and is thus not an independent variable.

It turns out that the distribution function  $f$ , defined this way, is independent of the choice of coord. system! We skip the proof of this important fact. (In CMB Physics 2004 it was done for the case of Minkowski space.) But note what is meant by it:

Consider a set of  $dN$  particles, all w momentum  $p_i$  (within  $d^3 p_i$ ) and location  $x^i$  (within  $d^3 x^i$ ) in one coord. system. Those same particles have a momentum  $p'_i$  (within  $d^3 p'_i$ ) and location  $x'^i$  (within  $d^3 x'^i$ ) in another coord. system. Note that the volume  $d^3 x'^i$  they occupy in the new coord. system depends on  $p_i$  (their velocity) -  $d^3 x^i$  cannot be transformed independently of  $p_i$ ! (See Figure 1, which



shows two sets of particles w different  $p_i$ .)

By definition the number of these particles is the same  $dN$  (since we consider a given set of particles) in both coord. systems. The claim is that the 6-dim volume elements are equal:

$$dx'^1 dx'^2 dx'^3 dp'_1 dp'_2 dp'_3 = dx^1 dx^2 dx^3 dp_1 dp_2 dp_3 \quad (2)$$

(This is the statement whose proof we skip.)

From this follows that

$$\underbrace{f(y', x_i', p_i')}_{\text{these refer to the same set of particles at the same spacetime event.}} = \underbrace{f(y, x_i, p_i)}_{\text{these refer to the same set of particles at the same spacetime event.}} \quad (3)$$

Thus  $f$  is a scalar quantity. For a given system, a given particle species, a given spacetime event  $P$ , and a given 4-momentum  $\underline{p}$  (appropriate for this particle species),  $f = f(P, \underline{p})$  is independent of the ref. system used to describe the system.

We shall use a global ref. system  $\{y, x_i\}$  in our discussion of the evolution of the distribution function. However, it is more convenient to use the 3-momentum  $q^i$  observed by a local observer instead of the covariant components  $p_i$  of the coordinate frame. For a given observer at a given spacetime event  $P$  we can always construct a locally orthonormal ref. system  $\{x^{\hat{i}}\}$  so that  $p_i = p^{\hat{i}} = q^i$  at  $P$ . Thus, at  $P$

$$dN = f(\hat{t}, x^{\hat{i}}, q^i) d^3 x^{\hat{i}} d^3 q^i = f(y, x_i, p_i) d^3 x_i d^3 p_i$$

Now  $\{x^{\hat{i}}\}$  do not remain orthonormal outside of  $P$ . On the other hand, in a given ref. system  $\{x^{\mu}\}$ , we can define for every spacetime event a comoving observer, one whose space coords  $x^i$  remain constant, and obtain the 3-momentum components  $q^i$  in his local orthonormal frame. We discuss the distribution function  $f$  in terms of these variables,  $f(y, x^i, q^i)$ . It is the same quantity and thus has the same value as before

$$f(y, x^i, q^i) = f(\hat{t}, x^{\hat{i}}, p^{\hat{i}}) = f(y, x_i, p_i),$$

but in terms of these variables

$$dN \neq f d^3 x^i d^3 q^i$$

since the  $q^i$  are not the conjugate momenta of  $x^i$ . Instead we have, since

$$dV = d^3 x^{\hat{i}} = \sqrt{\det(g_{j\hat{k}})} d^3 x^i$$

that

$$\underline{dN = f d^3 x^{\hat{i}} d^3 q^i = \sqrt{\det(g_{j\hat{k}})} \cdot f d^3 x^i d^3 q^i} \quad (4)$$

- From Statistical Physics, we have the important result:

Liouville Theorem: In the absence of collisions between particles,  $f$  stays constant along any particle trajectory in phase space,

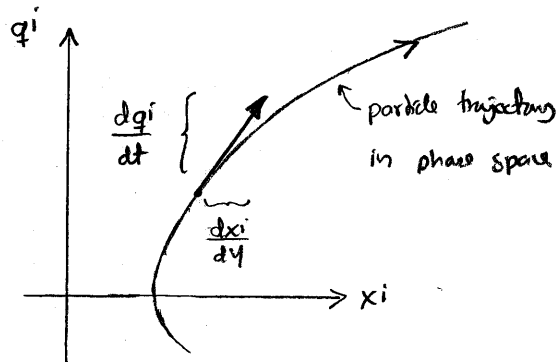
$$\frac{df}{dt} = 0 \quad (5)$$

- Since  $f$  has 7 variables,  $f = f(y, x_i, q_i)$ , we can write this in terms of partial derivatives,

$$\frac{df}{dt} = \frac{\partial f}{\partial y} + \frac{\partial f}{\partial x_i} \frac{dx_i}{dt} + \frac{\partial f}{\partial q_i} \frac{dq_i}{dt} = 0 \quad (6)$$

This is called the Collisionless Boltzmann Equation

where  $\frac{dx_i}{dt}$  describes the motion of the particle (w momentum  $q_i$ ) and  $\frac{dq_i}{dt}$  how its momentum changes in time.



- Instead of the three components of the locally observed momentum  $q_i$ , we could also use the variables

$$E \equiv \sqrt{\sum_i q_i^2 + m^2} \quad (7)$$

the particle energy observed by the local observer, and the angles  $\theta, \varphi$  specifying the direction

$$\hat{n} \equiv \frac{\vec{q}}{|\vec{q}|} \quad (8)$$

where the particle is going. So we can write (6) also as

$$\frac{df}{dt} = \frac{\partial f}{\partial y} + \frac{\partial f}{\partial x_i} \frac{dx_i}{dt} + \frac{\partial f}{\partial E} \frac{dE}{dt} + \underbrace{\frac{\partial f}{\partial \theta} \frac{d\theta}{dt} + \frac{\partial f}{\partial \varphi} \frac{d\varphi}{dt}}_{\text{"} \frac{\partial f}{\partial \hat{n}} \frac{d\hat{n}}{dt} \text{"}} = 0 \quad (9)$$

for  $f(y, x_i, E, \hat{n})$ .

(We could also use  $q \equiv |\vec{q}|$  instead of  $E$ :  $f(y, x_i, q, \hat{n})$ .)

- In the background universe the distribution function  $\bar{f}$  must be homogeneous and isotropic,

$$\bar{f}(y, x_i, E, \hat{n}) = \bar{f}(y, E) \quad (10)$$

⇒ the partial derivatives  $\frac{\partial \bar{f}}{\partial x_i}$  and  $\frac{\partial \bar{f}}{\partial \hat{n}}$  are perturbations.

- Since the background universe is isotropic, a free particle does not change direction in the bg universe.

⇒  $\frac{d\hat{n}}{dy}$  is a perturbation

$$\therefore \text{We have } \frac{d\bar{f}}{dy} = \underbrace{\frac{\partial \bar{f}}{\partial y}}_{1^{\text{st}} \text{ order}} + \underbrace{\frac{\partial \bar{f}}{\partial x_i} \frac{dx_i}{dy}}_{1^{\text{st}} \text{ order}} + \underbrace{\frac{\partial \bar{f}}{\partial E} \frac{dE}{dy}}_{1^{\text{st}} \text{ order}} + \underbrace{\frac{\partial \bar{f}}{\partial \hat{n}} \frac{d\hat{n}}{dy}}_{2^{\text{nd}} \text{ order}} = 0$$

Thus we have to 0<sup>th</sup> order

$$\frac{d\bar{f}}{dy} = \frac{\partial \bar{f}}{\partial y} + \frac{\partial \bar{f}}{\partial E} \frac{dE}{dy} = 0 \quad (11)$$

and to 1<sup>st</sup> order

$$\frac{d\bar{f}}{dy} = \frac{\partial \bar{f}}{\partial y} + \frac{\partial \bar{f}}{\partial x_i} \frac{dx_i}{dy} + \frac{\partial \bar{f}}{\partial E} \frac{dE}{dy} = 0 \quad (12)$$

We can write this as

$$\frac{\partial \bar{f}}{\partial y} = - \underbrace{\frac{\partial \bar{f}}{\partial x_i} \frac{dx_i}{dy}}_{\text{free streaming}} - \underbrace{\frac{\partial \bar{f}}{\partial E} \frac{dE}{dy}}_{\text{redshift}} \quad (13)$$

This result, the collisionless Boltzmann equation to 1<sup>st</sup> order, expresses how the value of the distribution function at  $x_i, q_i$  changes in time due to two effects:

- 1) Free streaming: Due to their velocities  $\frac{dx_i}{dy}$ , particles move out of the volume element  $d^3x_i$  (and thus from the phase space element  $d^3x_i d^3q_i$ ), and other particles move in.
- 2) Redshift: The energy (and thus the momentum) of the particle changes due to gravity.