

## A sidenote: Vector spaces, matrices and such

- **Vector space**  $V = \mathbb{R}^n$  (or  $V = \mathbb{C}^n$ ) in this chapter is defined as the set of all  $n$ -tuples (vectors)  $[x_1, \dots, x_n]$  with real (or complex) entries  $x_i$ .
  - Addition of vectors and multiplication by a scalar are defined.
- Let  $V$  be a vector space and let  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m \in V$ .
  - $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$  are **linearly dependent** if there is a set of scalars  $\alpha_1, \alpha_2, \dots, \alpha_m$ , with at least one nonzero such that
$$\alpha_1 \mathbf{v}_1 + \dots + \alpha_m \mathbf{v}_m = 0$$
  - $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$  are **linearly independent** if the only set of scalars  $\alpha_1, \alpha_2, \dots, \alpha_m$ , satisfying
$$\alpha_1 \mathbf{v}_1 + \dots + \alpha_m \mathbf{v}_m = 0$$
is the trivial choice of
$$\alpha_1 = \dots = \alpha_m = 0$$
  - $[\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m]$  is a **basis** for  $V$  if for every  $\mathbf{v} \in V$  there is a unique choice of scalars  $\alpha_1, \alpha_2, \dots, \alpha_m$  for which
$$\mathbf{v} = \alpha_1 \mathbf{v}_1 + \dots + \alpha_m \mathbf{v}_m$$
  - If  $V$  is a vector space with basis  $[\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m]$ , then every basis for  $V$  will contain exactly  $m$  vectors.
    - The number of  $m$  is called the **dimension** of  $V$ .

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- **Matrices** are rectangular arrays of real or complex numbers.
  - A general form of an  $m \times n$  matrix is
$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \dots & & & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$
  - Matrices have the following operations defined
    - **Addition** of two similarly shaped matrices: If  $\mathbf{A}$  and  $\mathbf{B}$  are  $m \times n$  matrices then their sum  $\mathbf{C} = \mathbf{A} + \mathbf{B}$  is defined as
$$c_{ij} = a_{ij} + b_{ij}.$$
    - **Multiplication by a scalar** ( $\alpha \in \mathbb{R}$ ):  $\mathbf{C} = \alpha \mathbf{A}$ ,  $c_{ij} = \alpha a_{ij}$
    - **Multiplication of two matrices**: Let  $\mathbf{A}$  be a  $m \times n$  matrix and  $\mathbf{B}$  a  $n \times p$  matrix. Their product  $\mathbf{C} = \mathbf{AB}$  is a  $m \times p$  matrix and is defined as
$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$
    - **Transpose** of a matrix  $\mathbf{A}$ ,  $\mathbf{C} = \mathbf{A}^T$  is defined as
$$c_{ij} = a_{ji}.$$
    - **Conjugate transpose** of a matrix  $\mathbf{A}$ ,  $\mathbf{C} = \mathbf{A}^*$  is defined as
$$c_{ij} = a_{ji}^*.$$

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- Following arithmetic equalities are easily proved:

$$\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A} \quad (\mathbf{A} + \mathbf{B}) + \mathbf{C} = \mathbf{A} + (\mathbf{B} + \mathbf{C}) \quad \mathbf{A}(\mathbf{B} + \mathbf{C}) = \mathbf{AB} + \mathbf{AC}$$

$$\mathbf{A}(\mathbf{BC}) = (\mathbf{AB})\mathbf{C} \quad (\mathbf{A} + \mathbf{B})^T = \mathbf{A}^T + \mathbf{B}^T \quad (\mathbf{AB})^T = \mathbf{B}^T \mathbf{A}^T$$

- Zero matrix has all elements zero and  $\mathbf{A} + \mathbf{0} = \mathbf{0} + \mathbf{A} = \mathbf{A}$

- Unit matrix  $\mathbf{1}$  of size  $n \times n$  is defined as

$$\mathbf{1} = [\delta_{ij}] = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 1 \end{bmatrix}.$$

- For all matrices  $\mathbf{A}$  of size  $m \times n$  and  $\mathbf{B}$  of size  $n \times p$  the following apply

$$\mathbf{A}\mathbf{1} = \mathbf{A}, \mathbf{1}\mathbf{B} = \mathbf{B}.$$

- Inverse of a  $n \times n$  matrix  $\mathbf{A}$  is defined as

$$\mathbf{AB} = \mathbf{BA} = \mathbf{1},$$

and is denoted by  $\mathbf{B} = \mathbf{A}^{-1}$ .

- **Row rank** of a  $m \times n$  matrix  $\mathbf{A}$  is the number of linearly independent rows in it (regarded as elements in vector space  $R^n$  (or  $C^n$ )). Similarly, **column rank** is the number of linearly independent columns. These numbers are always equal.

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• **Vector norm**  $\|\cdot\|$  (in vector space  $C^n$ ) is defined to have the following properties:

$$1) \|\mathbf{x}\| \geq 0, \forall (\mathbf{x} \in C^n) \text{ and } \|\mathbf{x}\| = 0 \text{ iff } \mathbf{x} = \mathbf{0}$$

$$2) \|\alpha\mathbf{x}\| = |\alpha|\|\mathbf{x}\|, \forall (\mathbf{x} \in C^n, \alpha \in R)$$

$$3) \|\mathbf{x} + \mathbf{y}\| \leq \|\mathbf{x}\| + \|\mathbf{y}\|, \forall (\mathbf{x}, \mathbf{y} \in C^n)$$

• **Matrix norm** of a square  $n \times n$  matrix  $\mathbf{A}$  satisfies — in addition to 1-3 — the following:

$$4) \|\mathbf{AB}\| \leq \|\mathbf{A}\| \|\mathbf{B}\|$$

5) There exists a vector norm  $\|\cdot\|_v$  that is *compatible* with the matrix norm:

$$\|\mathbf{Ax}\|_v \leq \|\mathbf{A}\| \|\mathbf{x}\|_v.$$

- Commonly the matrix norm used with a vector norm  $\|\cdot\|_v$  is defined as

$$\|\mathbf{A}\| = \max_{\|\mathbf{x}\|_v = 1} [\|\mathbf{Ax}\|_v]$$

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- Commonly used norms:

vectors

matrices

$$p\text{-norm: } \|\mathbf{x}\|_p = \left[ \sum_{i=1}^n |x_i|^p \right]^{1/p}$$

$$\|\mathbf{A}\|_p = \max_{\|\mathbf{x}\|_p = 1} [\|\mathbf{A}\mathbf{x}\|_p]$$

$$p = 1 \quad \|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|$$

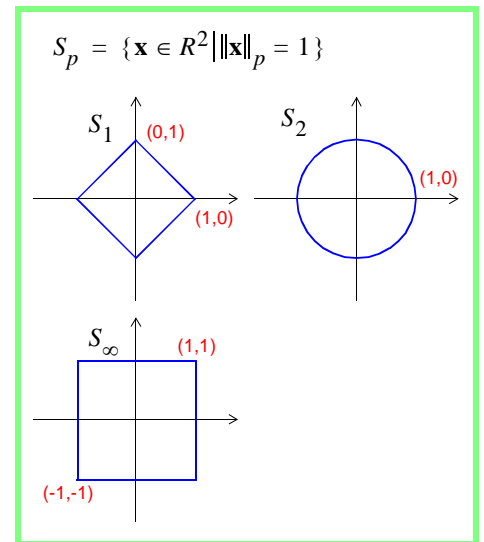
$$\|\mathbf{A}\|_1 = \max_{1 \leq j \leq n} \left[ \sum_{i=1}^n |a_{ij}| \right]$$

$$p = \infty \quad \|\mathbf{x}\|_\infty = \max_{1 \leq i \leq n} [|x_i|]$$

$$\|\mathbf{A}\|_\infty = \max_{1 \leq i \leq n} \left[ \sum_{j=1}^n |a_{ij}| \right]$$

$$p = 2 \quad \|\mathbf{x}\|_2 = \left[ \sum_{i=1}^n |x_i|^2 \right]^{1/2}$$

$$\|\mathbf{A}\|_2 = \sqrt{r_\sigma(\mathbf{A}^* \mathbf{A})},$$



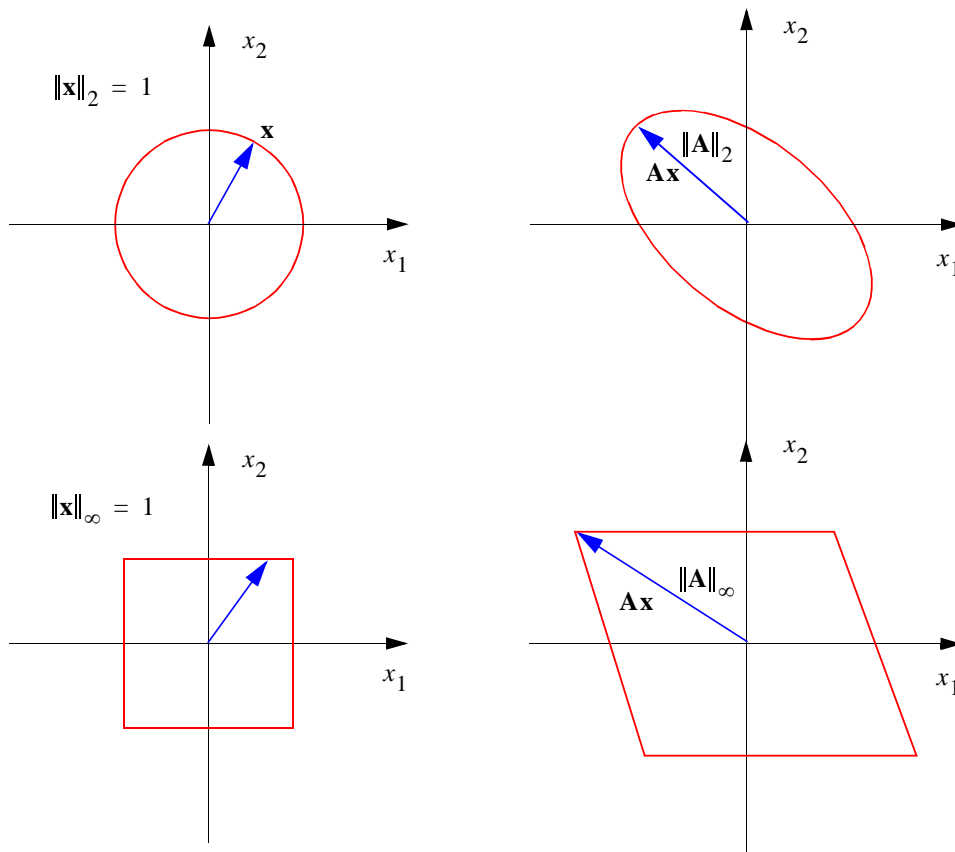
- Here  $r_\sigma(\mathbf{M})$  is the *spectral radius* of  $\mathbf{M}$ ; i.e. maximum size of its eigenvalues:  $r_\sigma(\mathbf{M}) = \max_{\lambda \in \sigma(\mathbf{M})} [|\lambda|]$ ,  
 $\sigma(\mathbf{M})$  is the *spectrum* of  $\mathbf{M}$ ; i.e. the set of its eigenvalues  
 $\mathbf{A}^*$  is the conjugate transpose of  $\mathbf{A}$ .

- Frobenius matrix norm  $\|\mathbf{A}\|_F = \left[ \sum_{i,j=1}^n |a_{ij}|^2 \right]^{1/2}$  can be shown to be compatible with the vector norm  $\|\mathbf{x}\|_2$ .

- The following holds for a square matrix  $\mathbf{A}$  and for any matrix norms of the type shown above:  $r_\sigma(\mathbf{A}) \leq \|\mathbf{A}\|$ .

## A sidenote: Vector spaces, matrices and such

- Geometric interpretation in 2D



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- **Rank, range** and **null space** of a matrix are concepts often needed in linear algebra.
  - They are defined as

let  $\mathbf{A}$  be an  $m \times n$  matrix

$\text{ran}(\mathbf{A}) = \{\mathbf{y} \in R^m; \mathbf{y} = \mathbf{A}\mathbf{x}; \mathbf{x} \in R^n\}$  (in some books also  $\text{range}(\mathbf{A})$ ; also called column space)

$\text{rank}(\mathbf{A}) = \dim(\text{ran}(\mathbf{A}))$  (same as the row or column rank above)

$\text{null}(\mathbf{A}) = \{\mathbf{x} \in R^n; \mathbf{A}\mathbf{x} = \mathbf{0}\}$